

DIFFERENTIAL OSCILLATOR CIRCUIT INCLUDING
AN ELECTRO-MECHANICAL RESONATOR

RELATED APPLICATION

This application is a continuation-in-part of U.S. patent application No. 10/162,714 filed on June 6, 2002 in the name of David Ruffieux and entitled "Differential oscillator circuit including an electro-mechanical resonator" which is assigned to the present Assignee.

TECHNICAL FIELD

- 5 The present invention generally concerns a differential oscillator circuit including an electro-mechanical resonator, in particular for an application as a timekeeper or precise reference frequency or in the field of telecommunications.

BACKGROUND ART

- Oscillator circuits are used in two main application categories. One of these applications is as a timekeeper or clock signal generator and the other is as a circuit
10 for making signal frequency translation possible in telecommunication devices.

- Electro-mechanical resonators, such as quartz resonators, are used, so to speak, systematically in applications as time-keeper, requiring a precise time base or when a precise reference frequency is desired, whereas the oscillator circuits used in radio-transmitters generally use LC tank circuits. The limited stability of the latter and
15 the large dispersion of their constitutive components often mandates their frequencies being slaved to a precise reference obtained from a crystal oscillator through a phase lock loop. There is no substantial difference in the circuits associated with these two types of resonators.

- In today's battery operated low power radio systems optimised for low bit-rate
20 communications with duty cycles typically below a few percents, a crystal oscillator has to run in permanence to maintain synchronization and organize a periodic wake-up of the system. The power consumption of this oscillator and its associated division chain is thus a critical parameter since, together with the leakage current of snoozed circuitry (e.g. RAM, μ P), it sets the static consumption of the radio system. On the
25 other hand, highly sensitive radio systems require a very accurate and stable time base since an emitter/receiver pair has to synthesize frequencies differing by no more

than a few ppm so that a narrowband communication channel can be established. Consequently, such systems require two time bases, a low power one (typically a 32 kHz time base as encountered in wristwatches) that runs permanently and ensures the period wake-up of the radio, and another one relying on a very accurate radio
5 crystal running intermittently but unfortunately at a much higher frequency and thus consuming a lot more power. This arrangement presents however several drawbacks, namely (i) the fact that two external bulky crystals are required, (ii) the fact that the limited precision of the 32 kHz time base implies more frequent wake-up or longer preamble thus increasing the duty cycle of the radio, and (iii) the fact that the accurate
10 time base needs to be powered up for each wake-up thus requiring an extra power consumption and degrading the resonator ageing.

Figure 1a shows a low consumption oscillator circuit 1 including a quartz resonator typically used in applications as timekeeper or frequency reference. The simplicity and high stability of this oscillator circuit have made it the most popular
15 crystal oscillator structure for low-power time bases found typically in wristwatch applications and for precise frequency reference for radio systems. This oscillator circuit 1, also known as a Pierce oscillator circuit or three-points oscillator circuit, thus includes a branch comprising a series arrangement, starting from a supply potential VDD to a supply potential VSS forming ground, of a current source 2 and a MOS
20 transistor 4 connected via its drain terminal to current source 2 and via its source terminal to potential VSS. A quartz resonator 6 and a resistive element R are connected in parallel between the connection node, indicated by the reference A, of current source 2 and transistor 4, and the connection node, indicated by the reference B, connected to the gate terminal of transistor 4. First and second load capacitive
25 elements C1 and C2 are respectively connected, via one of their electrodes, to connection nodes A and B, the other electrode being connected to supply potential VSS.

A linear analysis of the impedance presented by the circuit of Figure 1a including the static capacitance of the resonator, C_0 , leads to a bilinear function of the
30 transconductance g_m and thus a circle in the complex plane that allows the determination of the oscillator critical current, the exact frequency of oscillation, its sensitivity to quality factor Q, losses and loading capacitance variations and the maximum start-up current (cf. in particular E. A. Vittoz, M. G. R. Degrauwe and S. Bitz, "High-Performance Crystal Oscillator Circuits: Theory and Application", JSSC,
35 Vol. 23, No. 3, June 1988, pp. 774-783). To obtain a large circle radius and hence high stability, large loading capacitors are required thus increasing the oscillator power consumption.

If the circuit structure of the 3-points oscillator is duplicated and rendered symmetrical, the cross-coupled pair familiar to differential LC oscillator is obtained. Such a configuration is shown in Figure 1b. In this example, the circuit uses an LC tank circuit. This oscillator circuit, also globally indicated by the reference numeral 1, includes, placed in parallel between supply potentials VDD and VSS, first and second branches 10, 20 each including a series arrangement of a current source 2, respectively 3, and a transistor 4, respectively 5, connected by its drain terminal to the current source and via its source terminal to potential VSS. The LC tank circuit includes a capacitive element C placed in parallel to the series arrangement of a resistive element R, generally symbolising the arrangement losses, and an inductive element L.

Transistors 4 and 5 are connected in a differential configuration so as to form a crossed pair, i.e. the gate terminal of each transistor is connected to the drain terminal of the other transistor. Connection node A is thus formed of the connection node between current source 2, the drain terminal of transistor 4 and the gate terminal of transistor 5, and connection node B is formed of the connection node between current source 3, the drain terminal of transistor 5 and the gate terminal of transistor 4. The LC tank circuit is thus placed, in a similar manner to the quartz resonator of Figure 1a, between connection nodes A and B of the oscillator circuit, on the side of the drain terminals of transistors 4 and 5.

The differential structure of Figure 1b offers substantial advantages for high frequency applications, such as, particularly, reduced sensitivity to the supply and substrate noise, reduced harmonic pair content and limited substrate current injection.

The circuit implementation of Figure 1b is however not suitable for a resonator exhibiting a high DC impedance such as a crystal resonator since the circuit will merely latch in one of its two stable state, preventing a further oscillation build-up.

Differential oscillator circuit embodiment attempts using an electro-mechanical resonator have been proposed but have not, as yet, led to satisfactory solutions, mainly for reasons of stability. Figure 1c shows, for example, the prototype of a differential oscillator circuit employing a quartz resonator developed for the first electronic Swiss watch.

This circuit prototype includes two identical branches 10, 20 each including, starting from the supply potential VDD to the supply potential VSS, the series arrangement of a resistive element 8, respectively 9, of an n-MOS transistor 4, respectively 5, and a current source 2, respectively 3. The quartz resonator 6 is connected on the side of the source terminals of transistors 4 and 5 and, in a similar way to the circuit of Figure 1b, transistors 4 and 5 are connected in a differential

configuration, the gate terminal of each transistor being connected to the drain terminal of the other transistor.

As already mentioned, making the differential oscillator circuit of Figure 1c has not been brought to a successful conclusion for reasons of stability.

5 If the two sources of the cross-coupled pair are DC separated and capacitively coupled at high frequencies, the structure yields positive feedback only above a given frequency and is thus DC stable. A way to impose a similar biasing current above and below each of the two active transistors has to be found to yield a practical oscillator structure. Several such structures have been identified and are described in the
10 above-mentioned parent US patent application No. 10/162,714. Figure 2 shows one of these structures.

 The structure depicted in Figure 2 is, without the crystal resonator and the load capacitance, a well-known relaxation oscillator structure. It has already been proposed in International Application WO 98/48511 in association with an overtone crystal
15 resonator but in a coupled mode where the relaxation is synchronized by the high-Q resonator (cf. also J. R. Westra, C. J. M. Verhoeven and A. H. M. van Roermund, "Resonance-Mode Selection and Crosstalk Elimination Using Resonator-Synchronised Relaxation Oscillators", Proc. ESSCIRC 98, The Hague, The Netherlands, pp. 88-91).

20 In addition to the aforementioned oscillator circuits, it will be noted that recent developments in the manufacture of bulk acoustic wave resonators (or BAW resonators), offer new opportunities for applications in the field of telecommunications. Electro-mechanical BAW resonators, and more particularly, thin film BAW resonators have considerable advantages, in particular high working frequencies (of the order of
25 1 to 10 GHz), a high quality factor, reduced size and the possibility of being integrated directly onto the integrated circuit. By way of complementary information concerning BAW resonators, reference could be made to the document by MM. K. M. Lakin, K. T. McCarron and R. E. Rose, "Solidly Mounted Resonators and Filters", 1995 IEEE Ultrasonics Symposium, pp. 905-908.

30 The possibilities offered by the aforementioned BAW resonators require the development of dedicated circuits making use of all the advantages and excellent properties of these resonators.

SUMMARY OF THE INVENTION

One general object of the present invention is to propose an oscillator circuit based on the principle depicted in Figure 2 which is in particular suited, but not solely, to high frequency applications.

Another object of the present invention is to propose such an oscillator circuit,
5 which also has good stability and low power consumption.

Another more particular object of the present invention is to propose an oscillator circuit able, in particular, to make use of the advantages and excellent properties of the aforementioned BAW resonators.

The present invention thus concerns a differential oscillator circuit including an
10 electro-mechanical resonator whose features are listed in the independent claim 1.

Advantageous embodiments of the present invention form the subject of the dependent claims.

According to the invention, the differential oscillator circuit includes, in particular, first and second branches each including a series arrangement of a
15 transistor connected via its current terminals and bias means imposing a determined current through the transistor. The transistors are connected, in a similar way to the prior art, in a differential configuration, the control terminal of each transistor being connected to the current terminal of the other transistor having the most positive potential, like the drain terminal of the transistors in the event that the latter are made
20 in MOS technology.

More particularly, according to the invention, the electro-mechanical resonator is connected between the control terminals of the transistors, namely on the side of the current terminals of the transistors having the most positive potential, like the drain terminals of MOS technology transistors. Moreover, a capacitive element is placed
25 between the current terminals of the transistors having the most negative potential, namely the source terminals of MOS transistors.

The various embodiments, which will be described in the following description, are based on MOS technology. Although not explicitly shown, the dual versions of these embodiments (obtained by reversing the supply voltages and the polarities of
30 the transistors) are also deemed to form part of the invention. Furthermore, it will likewise be understood that the present invention is not limited to this specific technology and that the transistors could, if required, be made in bipolar technology.

The invention proposes, for the first time, an efficient solution relying on an oscillator circuit with a differential structure including an electro-mechanical resonator.

Unlike the differential resonator of Figure 1c, which has a stability problem, the oscillator circuit according to the present invention has great stability and essentially behaves like the oscillator circuit of Figure 1b in proximity to the resonant frequency of the LC tank circuit. The capacitive element placed on the source side with respect to
5 the crossed pair of transistors fixes the frequency below which the stability of the continuous DC component – or negative counter-reaction – dominates, and above which oscillation occurs. In addition, the capacitance value of this capacitive element is selected so that relaxation of the circuit is prevented.

According to the invention, the bias means can regulate the oscillation
10 amplitude if they are placed in a low frequency regulating loop following an amplitude detector.

From the point of view of consumption, the oscillator circuit according to the present invention performs better than the Pierce oscillator illustrated in Figure 1a, since the load capacitive elements C1 and C2 placed on either side of the Pierce
15 resonator are omitted, according to the present invention, without modifying the behaviour of the circuit and without being detrimental to frequency stability of the oscillator.

BRIEF DESCRIPTION OF THE DRAWINGS

Other features and advantages of the present invention will appear more clearly upon reading the following detailed description, made with reference to the
20 annexed drawings given by way of non-limiting example and in which:

- Figure 1a, which has already been described, shows a diagram of an oscillator circuit with an electro-mechanical resonator, known by the name of a Pierce resonator;
- Figure 1b, which has already been described, shows a diagram of a
25 differential oscillator circuit including an LC tank circuit;
- Figure 1c, which has already been described, shows a diagram of a differential oscillator circuit prototype including an electro-mechanical resonator envisaged for the first electronic Swiss watch;
- Figure 2 shows a differential oscillator circuit constituting a first embodiment
30 of the present invention;
- Figure 3 shows an equivalent small signal circuit of the embodiment of Figure 2; and
- Figure 4 shows a differential oscillator circuit constituting an improved variant of the first embodiment of Figure 2.

EMBODIMENTS OF THE INVENTION

Figure 2 shows a diagram of a differential oscillator circuit, globally indicated by the reference numeral 1, constituting a first embodiment of the present invention.

This differential oscillator circuit 1 includes, generally, first and second branches, respectively designated by the reference numerals 10 and 20, each
5 connected between a high supply potential VDD and a low supply potential VSS. These branches are identical and each include, starting from high supply potential VDD, the series arrangement of a resistive element 8, respectively 9, an n-MOS transistor 4, respectively 5, and a current source 2, respectively 3. More specifically,
10 drain of transistor 4, and the other is connected between supply potential VDD and the drain of transistor 5. Likewise, one of current sources 2, 3 is connected between supply potential VSS and the source of transistor 4, and the other is connected between supply potential VSS and the source of transistor 5.

Current sources 2, 3 and resistive elements 8, 9 together form bias means that
15 impose a determined current through transistors 4, 5, which current is the same in the two circuit branches 10 and 20.

Transistors 4, 5 form a crossed pair of transistors. In this configuration, the drain of transistor 4 of first branch 10 is connected to the gate of transistor 5 of the other branch 20 and, symmetrically, the drain of transistor 5 of second branch 20 is
20 connected to the gate of transistor 4 of first branch 10.

According to the invention, differential oscillator circuit 1 further includes an electro-mechanical resonator 6 connected via first and second terminals 6a, 6b between the drains of transistors 4 and 5 of the two branches 10, 20. These first and second terminals 6a, 6b of electro-mechanical resonator 6 also form the first and
25 second output terminals of the differential oscillator circuit.

This electro-mechanical resonator 6 may be a continuous quartz resonator with high impedance in steady state or, with a view to use for high frequency applications (within a range of the order of 1 to 10 GHz), advantageously a bulk acoustic wave resonator like the BAW resonators mentioned in the preamble or, again, so-called
30 "TFBAR" resonators (Thin Film Bulk Acoustic Resonators).

Differential oscillation circuit 1 according to the invention further includes a capacitive element 7 of capacitance C_s connected between the sources of transistors 4, 5. This capacitive element 7 fixes the frequency below which the DC stabilisation (or negative counter-reaction) dominates and above which oscillation can occur and,

depending on its value, whether parasitic relaxation oscillations could occur.

Capacitance C_L designates the capacitance seen between the two drains of the cross-coupled n-MOS pair and is indicated here for the purpose of explanation.

Generally, and as will be seen in detail hereinafter with reference to the second
5 embodiment of the present invention, current sources 2, 3 can allow regulation of the oscillation amplitude if placed in a suitable oscillation amplitude regulating loop.

As already mentioned in the preamble, the structure illustrated in Figure 2 performs better in terms of power consumption than the Pierce oscillator circuit illustrated in Figure 1a. Indeed, the use of load capacitive elements on either side of
10 the electro-mechanical resonator can be omitted without altering the behaviour or frequency stability of the oscillator.

A small-signal analysis of the impedance (or admittance) seen outside the motional branch of the crystal oscillator ($R_m L_m C_m$) allows a precise determination of the conditions leading or not to relaxation. With C_O the shunt capacitance of the
15 crystal resonator, C_L , C_S the equivalent differential capacitances seen respectively between the two drains and the two sources of the cross-coupled n-MOS pair, gm their transconductance, n the transistor body effect and R , the value of the biasing resistor, the circuit impedance can be computed with the equivalent circuit shown in Figure 3.

20 The impedance is again a bilinear function of gm . Thanks to biasing resistors 8, 9, the real part of the impedance is positive at low frequency, hence the stability of the circuit, and drops to negative value yielding gain above a frequency ω given by expression (1) below :

25
$$\omega = \frac{n \cdot gm}{2 \cdot C_S} \cdot \sqrt{\frac{1}{gm \cdot R - 1}} \quad (1)$$

The reactance of the circuit is null at a frequency ω given by the following expression :

30
$$\omega = \frac{n \cdot gm}{2 \cdot C_S} \cdot \sqrt{\frac{C_S}{n \cdot (C_L + C_O)}} \quad (2)$$

Depending on the value of the different capacitors, it may be appreciated that frequency ω will have a complex or real root. In particular, frequency ω will be complex if the following condition is satisfied :

$$C_S < n \cdot (C_L + C_O) \quad (3)$$

If frequency ω is complex, this then means that the phase can never be null and that relaxation cannot happen. If the value of capacitance C_S is increased beyond the value defined in expression (3) above, there exists a frequency where the phase is null. If the resistance of the circuit is null or negative at this frequency, then all the conditions are satisfied for the circuit to enter relaxation. Accordingly, relaxation of the circuit can be prevented, as a general rule, if the frequency for which the reactance is null has a complex root.

10 Provided the negative resistance is sufficiently big, oscillations can build up at a frequency f_{osc} that is :

$$f_{osc} = \frac{1}{2\pi\sqrt{L_m \cdot C_m}} \left[1 + \frac{C_m}{2 \cdot (C_O + C_L)} \right] \quad (4)$$

15 The locus of the impedance in the complex plane as g_m is varied for different values of C_S is a family of circles of various radiuses R_C given by :

$$R_C = \frac{1}{2} \frac{C_S}{n \cdot (C_L + C_O) - C_S} \frac{1}{\omega_0 \cdot (C_L + C_O)} \quad (5)$$

20 C_L which is equivalent to the load capacitance of the 3-points oscillator should thus be minimized to obtain a large circle and hence a high stability.

Interestingly, if capacitance C_S is chosen so that the circuit reactance is null at $\omega=0$ (e.g. $C_S = n \cdot (C_L + C_O)$), the circle radius tends towards infinity. If C_S is 80% of that value, and C_L negligible with respect to C_O , the circle radius is still four times bigger than the maximum 3-points circle with $C_L = \infty$. Again, when C_S is increased beyond that value, the impedance locus crosses the imaginary axis in the left half plane enabling relaxation. With the circuit of Figure 2, capacitance C_S should thus preferably be kept between 80% to 100% of its maximum value preventing relaxation.

We will now turn to power consumption issues of the circuit configuration shown in Figure 2. The summed critical transconductance g_{m_c} necessary to overcome the resonator losses as a function of the resonator Q-factor is independent of C_S and given by :

$$gm_C = 4 \left[\sqrt{\frac{C_m}{L_m}} \left(\frac{C_m}{C_O} \right)^{-2} \frac{1}{Q} \right] \left(1 + \frac{C_L}{C_O} \right)^2 + \frac{1}{R} \quad (6)$$

Assuming $1/R$ negligible, this value is identical to that of a 3-points oscillator with a similar load capacitance. Minimizing the term in the first bracket is the matter of crystal manufacturers. Consequently, the only way to reduce the oscillator power consumption is to reduce the load over shunt capacitance ratio (C_L/C_O). This would intuitively be in contradiction with stability issues. Let us however make a partial derivation of equation (4) to compute the sensitivity of the oscillation frequency to a relative variation of load capacitance C_L . It yields :

$$\frac{\Delta f_{OSC}}{f_{OSC}} = - \frac{C_m}{2C_O} \frac{C_L}{C_O} \left(1 + \frac{C_L}{C_O} \right)^{-2} \frac{\Delta C_L}{C_L} = \quad (7)$$

Interestingly, the factor that depends on the C_L over C_O ratio is a symmetrical function of the load over shunt capacitance ratio C_L/C_O (i.e. $f(C_L/C_O) = f(C_O/C_L)$). In other words, the improved stability that is obtained by choosing a large loading capacitance C_L (at the expense of a serious increase in the power consumption) can also be achieved without any penalty in terms of power consumption if the inverse C_L over C_O ratio can be attained. Let us for instance consider a ratio C_L/C_O of 3 or $1/3$, the stability is the same but there is a difference in terms of power consumption of a factor 10.

In the 3-points oscillator structure, load capacitance C_L is a functional element and a reduction of its value leads to a reduction of the impedance circle in the complex plane which could prevent oscillations if C_L turns to be too small. In the differential oscillator structure of Figure 2 however, the effect is opposite. If the load capacitance C_L is reduced, both the stability and the power consumption are improved as demonstrated hereinabove. Within the scope of the present invention, the load capacitance C_L can thus be reduced to parasitics, i.e. that of the PCB, of the IC pad, of its ESD protection device and of the junctions and gates of the transistors.

The differential oscillator structure presented in Figure 2 for analysis purposes suffers however from some drawbacks. A first drawback resides in that the biasing resistors 8, 9 should be prohibitively large not to deteriorate the resonator quality factor Q . Another drawback resides in the fact that the oscillator common mode voltage depends linearly on the current drawn by the bottom current sources 2, 3, thus

limiting the maximum start-up current. Those drawbacks can be avoided with the structure shown in Figure 4.

In that implementation, the biasing resistors are replaced by two current sources comprising p-MOS transistors M8 and M9 (which are part of a current mirror comprising transistors M7, M8, M9). The bottom current sources are replaced by n-MOS transistors M3 and M4 whose gate terminals are connected to the resonator terminals 6a, 6b. Transistors M3, M4 work in the triode region as current followers forcing the current delivered by transistors M8, M9 across the cross-coupled pair M1, M2 (which correspond to transistors 4, 5 in Figure 2).

Owing to the symmetry of the structure and its DC stability, the common mode voltage at the quartz ports 6a, 6b before oscillations build-up is simply the one that would appear across a diode-connected stack of two transistors identical to that of one branch. This is exploited to realise the degenerated current mirror M5, M6 which together with transistors M1 to M4, M7 to M9, and resistors R16, R17 and RPTAT (resistor R1 and capacitor C1) form an amplitude regulation loop inspired from the one found in some 3-points quartz oscillators. Alternatively, native transistors having a threshold voltage V_T close to zero and operating in the sub-threshold region may be used instead of resistors R16, R17 for the extraction of the oscillator common mode voltage so that they can be biased without requiring a gate voltage higher than the channel one.

An analysis of the impedance presented by the circuit of Figure 4 leads to the criteria preventing relaxation. While the impedance is not a bilinear function of transconductance g_m anymore, its locus remains close to a circle and the "radius" is still dependant on C_S and can thus also be made rather large even if C_S is controlled within 20% tolerance. Consequently, all the advantages derived for the structure presented in Figure 2 are preserved.

The condition on C_S that is to be met so that relaxation of the circuit does not occur is slightly different than that given in expression (3) above in connection with the structure of Figure 2 :

30

$$C_S < n/2 \cdot (C_L + C_O) (1 + S3/S1)^2 \quad (3)$$

where S3 and S1 are respectively the number of transistors forming transistor M3 and transistor M1 (transistors M2 and M4 being identical to transistors M1 and M3 respectively and the number of transistors forming M3/M4 being greater than M1/M2 for DC stability reason (real part of impedance positive at DC)).

The general rule stated above is however still applicable, namely capacitance C_S has to be chosen so that the reactance of the circuit does not have any real zero (but a complex zero). In any case, for each structure, there is a value for capacitance C_S which corresponds to the circuit reactance being null at a frequency equal to zero (5 $\omega = 0$). This determines a maximum value for C_S , which should not be exceeded in order to prevent relaxation of the circuit. The value of capacitance C_S should be chosen as close as possible to this maximum, taking account of the tolerances on capacitances C_L and C_O , so as to maximize the "radius" of the impedance locus.

It will be understood that various modifications and/or improvements obvious to (10 those skilled in the art can be made to the embodiment described in the present description without departing from the scope of the invention defined by the annexed claims. Thus, as already mentioned, the differential oscillator circuit according to the present invention could perfectly well be made in bipolar technology.